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$p(R|H_1)dR =$   
 $P_0C_{10} + P_1C_{11} + Z \cdot Z_0.$   
 $\{P_1(C_{01} - C_{11})p(R|H_1) -$   
 $P_0(C_{10} -$   
 $C_{00})p(R|H_0)\}dR$  (2) If  
we introduce the  
probability of false  
alarm  $P_F$ , the

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probability of detection  
PD, and the probability  
of a miss PM, as de?ned  
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Theory. Author(s):

Harry L. Van Trees;

First published: 27

September 2001. ...

HARRY L. VAN

TREES, ScD, was

Professor of Electrical

Engineering at

Massachusetts Institute

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the probability of false alarm  $P_F$ , the probability of detection  $P_D$ , and the probability of a miss  $P_M$ , as defined in the book, we find that  $R$  given via Equation 1 becomes when we use  $R$

$$Z_0 \int_{Z_0}^{\infty} p(R|H_0) dR + Z_1 \int_{-\infty}^{Z_0} p(R|H_0) dR = Z_0$$

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"Detection, Estimation,  
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Part I," John Wiley,

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Harry L. Van Trees (M'  
57–SM'73–F'74–LF'94)  
received the B.Sc.  
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Military Academy, West  
Point, NY, in 1952 and  
the Sc.D. degree from

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the Massachusetts  
Institute of Technology  
(MIT), Cambridge, in  
1961. From 1961 to  
1975, he was with the  
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Harry Leslie Van Trees

is a scientist specializing  
in radar, sonar,  
communications and  
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Trees; H. David  
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Intersci., 2001. [6] C. R.  
Rao, Linear Statistical  
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Principles of

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Engineering. 2. ...

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Session 5.1 Final Exam.

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EE 631: Detection and  
Estimation Theory, Fall  
2006

Abstract. A comparison  
of different methods to  
estimate the sun-  
direction vector using a  
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underdetermined set of cosine-type coarse sun sensors (CSS), while simultaneously controlling the attitude towards a power-positive orientation, is presented.

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